

Lecture 16: Phase Space

Point in phase space \vec{X}_i (our book uses \vec{z} , but \vec{X}_i is more traditional and fun to write).
over-bar means n-tuple, array of numbers.

$$\vec{X} = (\vec{q}, \vec{p}) = (q_1, \dots, q_N; p_1, \dots, p_N)$$

N is number of degrees of freedom of system.

Initial conditions of system define a unique point in phase space. Time evolution gives phase space orbit; phase space orbits never cross if H is conserved.

Simple Example 1

Harmonic oscillator: $T = \frac{1}{2} m \dot{x}^2$
 $U = \frac{1}{2} m \omega^2 x^2$

$$p = \frac{\partial \mathcal{L}}{\partial \dot{x}} = m \dot{x}$$

$$H = T + U = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

$$\dot{x} = \frac{\partial H}{\partial p} = \frac{p}{m} \quad ; \quad \dot{p} = -\frac{\partial H}{\partial x} = -m \omega^2 x$$

clean this up a bit by defining

$$x' \equiv \sqrt{m\omega} x \quad \text{and} \quad p' \equiv p / \sqrt{m\omega}$$

then $\dot{x}' = \omega p'$

$$\dot{p}' = -\omega x'$$

$$\frac{d}{dt} \begin{pmatrix} x' \\ p' \end{pmatrix} = \omega \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x' \\ p' \end{pmatrix}$$

uncouple: $\ddot{x}' = \omega \dot{p}' = -\omega^2 x'$

$$x'(t) = x_0' \cos \omega t + p_0' \sin \omega t$$

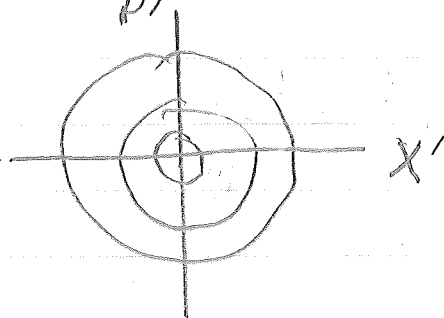
$$p'(t) = \frac{1}{\omega} \dot{x}' = x_0' (-\sin \omega t) + p_0' \cos \omega t$$

$$\begin{pmatrix} x'(t) \\ p'(t) \end{pmatrix} = \begin{pmatrix} \cos \omega t & \sin \omega t \\ -\sin \omega t & \cos \omega t \end{pmatrix} \begin{pmatrix} x_0' \\ p_0' \end{pmatrix}$$

rotation in phase space

$$x'^2 + p'^2 = x_0'^2 + p_0'^2 = \text{const}$$

$$E = H = \frac{1}{2} \omega (x'^2 + p'^2)$$



circles in phase space.

Each circle corresponds to different value of w .

Example 2: Uniform acceleration

$$H = T + U = \frac{p^2}{2m} - mgx$$

$$\dot{x} = \frac{\partial H}{\partial p} = \frac{p}{m}$$

$$\dot{p} = -\frac{\partial H}{\partial x} = mg$$

force $u = -\vec{\nabla}U$

$$p(t) = mat + p_0$$

$$\dot{x} = at + p_0/m; \quad x(t) = \frac{1}{2}at^2 + \frac{p_0}{m}t + x_0$$

consider four trajectories:

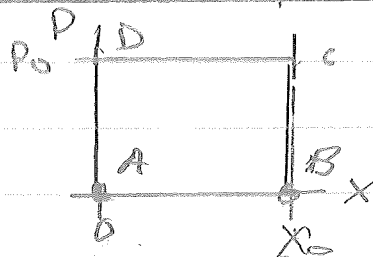
$$\xi_A = (0, 0)$$

$$\xi_B = (x_0, 0)$$

$$\xi_C = (x_0, p_0)$$

$$\xi_D = (0, p_0)$$

Volume in phase space (2D space is an area)



$$V = x_0 p_0$$

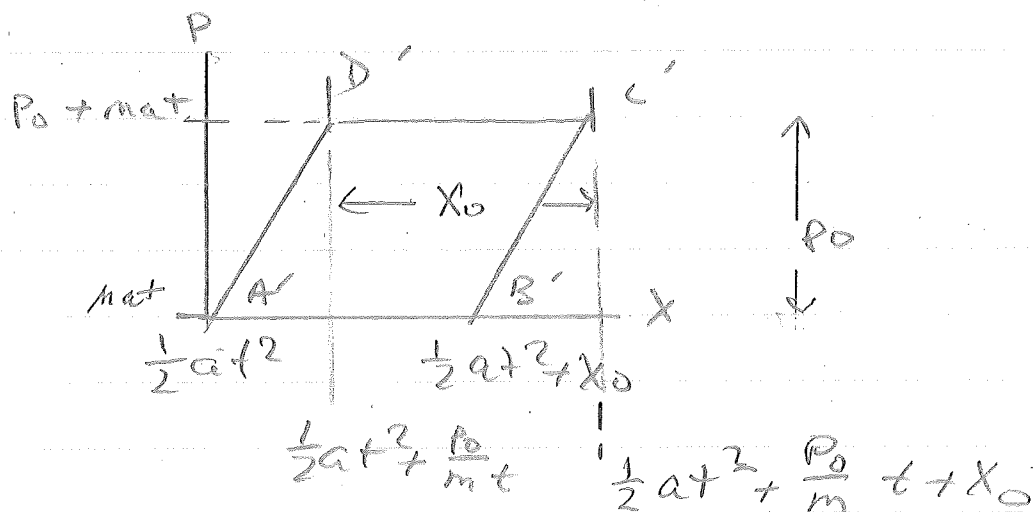
After time t :

$$\vec{r}'_A = \left(\frac{1}{2}at^2, mat \right)$$

$$\vec{r}'_B = \left(\frac{1}{2}at^2 + x_0, mat \right)$$

$$\vec{r}'_C = \left(\frac{1}{2}at^2 + \frac{p_0}{m}t + x_0, mat + p_0 \right)$$

$$\vec{r}'_D = \left(\frac{1}{2}at^2 + \frac{p_0}{m}t, mat + p_0 \right)$$



$$V' \text{ is parallelogram} \hat{=} \overrightarrow{A'B'} = x_0 \hat{x}$$

$$\overrightarrow{A'D'} = \frac{p_0}{m}t \hat{x} + p_0 \hat{y}$$

$$V' = \left| \overrightarrow{A'B'} \times \overrightarrow{A'D'} \right| = x_0 p_0$$

This is an example of Liouville's Theorem.