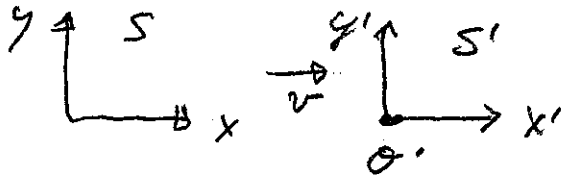


HW #1 Solutions

① A boost leaves  $\bar{x} \cdot \bar{x} = t^2 - x^2$  invariant



$\bar{O}' \rightarrow (t, vt)$  ,  $\bar{O}' \rightarrow (t', 0)$   
frames frames'

$$\begin{pmatrix} t' \\ x' \end{pmatrix} = \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix} \begin{pmatrix} t \\ x \end{pmatrix}$$

$$x' = 0 = t(B_{21} + B_{22}v), \quad v = -B_{21}/B_{22}$$

$t'^2 - x'^2 = t^2 - x^2$  leads to 3 equations

$$1. B_{11}^2 - B_{12}^2 = 1$$

$$2. B_{11}B_{12} - B_{21}B_{22} = 0$$

$$3. B_{22}^2 - B_{12}^2 = 1 = B_{22}^2(1 - v^2) = 1$$

$$B_{22} = 1/\sqrt{1-v^2} \equiv \gamma$$

$$2. \text{ gives } B_{11}B_{12} = -v\gamma^2$$

Substitution in 1. gives  $B_{11}^2 - \frac{v^2\gamma^4}{B_{11}^2} = 1 \Rightarrow B_{11} = \gamma$

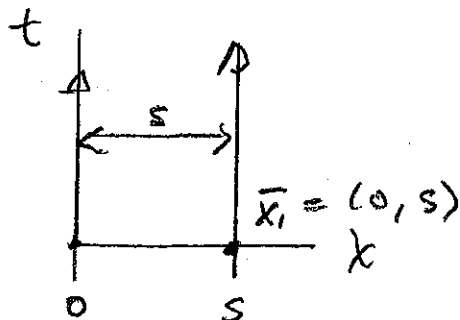
so the boost is  $\begin{pmatrix} \gamma & -v\gamma \\ -v\gamma & \gamma \end{pmatrix}$

det. then  $\begin{pmatrix} \gamma & -v\gamma \\ -v\gamma & \gamma \end{pmatrix} = \gamma^2(1 - v^2) = 1$

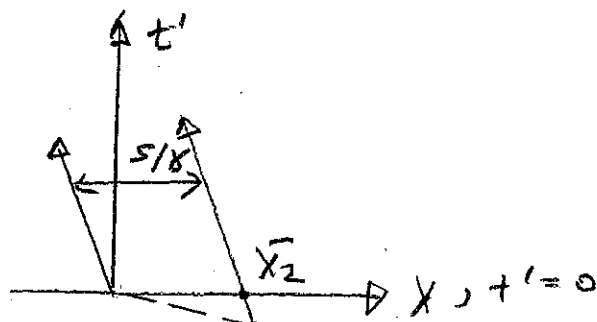
② proper length

Define frames  $S, S'$  as in problem ①

The object is of length  $s$  at rest in the unprimed frame. A sketch of the worldline of the left and right ends in frame  $S$ ,



In the primed frame,



$$\begin{pmatrix} t'_1 \\ x'_1 \end{pmatrix} = \begin{pmatrix} \gamma & -v\gamma \\ -v\gamma & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ s \end{pmatrix} = \begin{pmatrix} -v\gamma s \\ \gamma s \end{pmatrix}$$

at  $t'=0$ , the right end of the object is at

$$x'_2 = \gamma s - v(v\gamma s) = \gamma s (1 - v^2) = s/\gamma$$

So length of moving object, measured at  $t'=0$

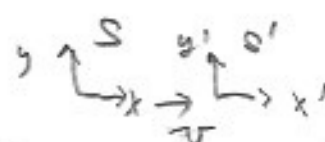
is  $s/\gamma$ . Length of moving object is

contracted.

#3

$$\tanh \theta = v$$

$$\bar{B}(\theta) = \begin{pmatrix} \cosh \theta & -\sinh \theta \\ -\sinh \theta & \cosh \theta \end{pmatrix}$$

  
use +1 de for 4-vel  
when  $\tilde{x} = (t, x)$   
first x space component

$$\begin{aligned} \bar{B}(\theta_1) \cdot \bar{B}(\theta_2) &= \begin{pmatrix} c_1 & -s_1 \\ -s_1 & c_1 \end{pmatrix} \begin{pmatrix} c_2 & -s_2 \\ -s_2 & c_2 \end{pmatrix} \\ &= \begin{pmatrix} c_1 c_2 + s_1 s_2 & -c_1 s_2 - s_1 c_2 \\ -s_1 c_2 + c_1 s_2 & s_1 s_2 + c_1 c_2 \end{pmatrix} \\ &= \begin{pmatrix} \cosh(\theta_1 + \theta_2) & -\sinh(\theta_1 + \theta_2) \\ -\sinh(\theta_1 + \theta_2) & \cosh(\theta_1 + \theta_2) \end{pmatrix} = \bar{B}(\theta_1 + \theta_2) \end{aligned}$$

hyperbolic trig identities

Addition of velocities  $\tanh \theta_{12} = v_{12}$

$$v_{12} = \frac{\tanh \theta_1 + \tanh \theta_2}{1 + \tanh \theta_1 \tanh \theta_2} = \frac{v_1 + v_2}{1 + v_1 v_2}$$

#4 (3.3)

(a) Volume  $V = \Delta x \cdot \Delta y \cdot \Delta z$

under L.T. in x direction,  $V' = \frac{\Delta x'}{\gamma} \cdot \Delta y \cdot \Delta z = \frac{V}{\gamma}$

(b) density  $\rho = \frac{N}{V}$   $N$  is Lorentz invariant  
so  $\rho' = \gamma \rho$

#5 (3.4) (a)  $d_{NR} = v \Delta t$

(b) In earth frame  $\Delta t = \gamma \Delta \tau$  ( $\tau$  proper time)

distance  $d = v \Delta t = v \gamma \Delta \tau = \gamma d_{NR}$

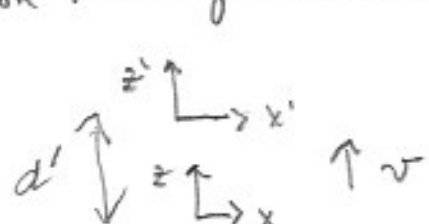
$\gamma(v=0.998) = 15.8$

$d_{NR} = (2.2 \times 10^{-6} \text{ sec}) (3 \times 10^8 \text{ m/s}) = 660 \text{ m}$

$d = 10.3 \text{ km}$

(c) in muon rest frame (primed)

$d' = \Delta \tau v = \frac{d}{\gamma}$



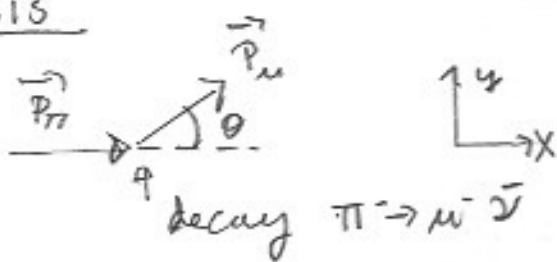
(d) distance traveled is Lorentz contracted.

Charged Pion lifetime  $\pi^+$  is  $\tau_{\pi^+} = 2.6 \times 10^{-8} \text{ s}$

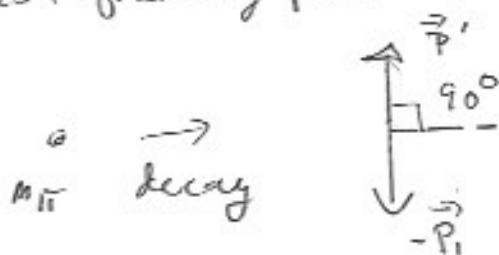
$d_{\pi^+} = \gamma \Delta \tau c = 122 \text{ m} = 0.1 \text{ km}$

charged pion does not make it to ground, but neutrinos do.

#6 3.15



In rest frame of pion (zero 3 momentum frame)



Write four vector w/o z component as

$\tilde{p} = (E, p_x, p_y)$  then in pion rest frame

4-momentum conservation is

$$(m_\pi, 0, 0) = (E'_\mu, 0, p') + (p', 0, -p') \quad (m_\nu = 0)$$

$$m_\pi = E'_\mu + p' = \sqrt{m_\mu^2 + p'^2} + p'$$

$$p' = \frac{m_\pi}{2} \left( 1 - \frac{m_\mu^2}{m_\pi^2} \right) \equiv \frac{m_\mu}{2} (1 - \beta^2) \quad \beta = \frac{m_\mu}{m_\pi}$$

Transform to Lab frame

$$\begin{pmatrix} E \\ p_x \\ p_y \end{pmatrix}_\mu = \begin{pmatrix} \gamma & \gamma v & 0 \\ \gamma v & \gamma & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E'_\mu \\ 0 \\ p' \end{pmatrix}$$

$$E'_\mu = \sqrt{m_\mu^2 + p'^2}$$

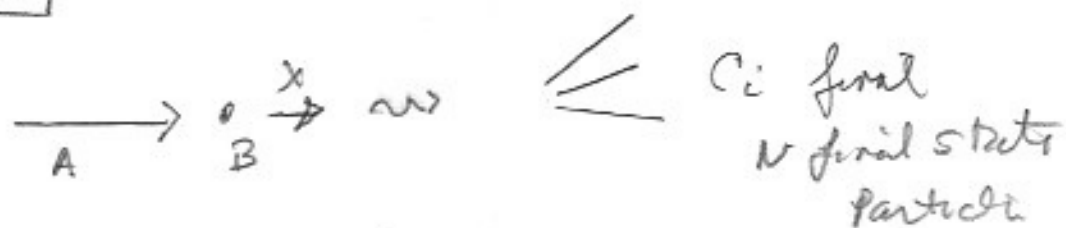
$$\tan \theta = \frac{p'_y}{p'_x} = \frac{p'}{\gamma v E'_u} \xrightarrow{m_u \rightarrow 0} \frac{1}{\gamma v}$$

this is called the headlight effect.

$$\begin{aligned} \left( \frac{E'_u}{p'} \right)^2 &= \frac{m_u^2 + p'^2}{p'^2} = \frac{m_\pi^2 (r^2 + m_\pi^2 p'^2)}{p'^2} \\ &= m_\pi^2 \left[ \frac{r + \frac{1}{4}(1-r^2)}{\frac{m_\pi^2}{4}(1-r^2)^2} \right] \\ &= \frac{4r^2 + 1 - r^2}{(1-r^2)^2} = \frac{3r^2 + 1}{(1-r^2)^2} \end{aligned}$$

$$\tan \theta = \left( \frac{1}{\gamma v} \right) \frac{1-r^2}{\sqrt{3r^2+1}}$$

#7, 3, 16



In zero 3 momentum frame

$$P'_F = (M, \vec{0})$$

$$M = \sum_{i=1}^N m_i \quad \text{sum of masses}$$

with 4-momentum dropping irrelevant y, z components

$$\tilde{P}_{TOT} = (E_A, p_A) + (m_B, 0)$$

$$P'_{TOT} = (M, 0)$$

4-vector dot product is L.I.

$$\tilde{P}_{TOT} \cdot \tilde{P}_{TOT} = (E_A + m_B)^2 - p_A^2 = M^2$$

$$E_A = \sqrt{m_A^2 + p_A^2}$$

$$E_A^2 + 2m_B E_A + m_B^2 - p_A^2 = M^2$$

$$2m_B E_A = M^2 - m_A^2 - m_B^2$$

$$E_A = \frac{1}{2m_B} [M^2 - m_A^2 - m_B^2]$$