

Lecture #1 Some Math

Quantum position states are vectors in an abstract space of complex functions with a (Unitary) inner product: Hilbert space.

Euclidean vectors:  $\vec{F} = (x_1, x_2, x_3)$  coordinates  
 $\vec{F} \cdot \vec{F} = (x_1^2 + x_2^2 + x_3^2)$  norm

norm invariant under rotations.

orthogonal, unit vectors

$$\hat{e}_i \cdot \hat{e}_j = \delta_{ij}$$
$$\vec{F} = \sum_{i=1}^3 x_i \hat{e}_i$$

Dirac vector notation:  $|v\rangle$  "ket"

linear vector space  $\{|v\rangle\}$

① addition  $|c\rangle = |a\rangle + |b\rangle$

② scalar multiplication distributive over vectors

$$a(|v\rangle + |w\rangle) = a|v\rangle + a|w\rangle$$

③ scalar multiplication distributive in scalars

$$(a+b)|v\rangle = a|v\rangle + b|v\rangle$$

④ scalar multiplication associative

$$a(b|v\rangle) = ab|v\rangle$$

⑤ addition commutative

$$|v\rangle + |w\rangle = |w\rangle + |v\rangle$$

⑥ addition associative

$$|v\rangle + (|w\rangle + |z\rangle) = (|v\rangle + |w\rangle) + |z\rangle$$

- (7) exists null vector  $|0\rangle + |v\rangle = |v\rangle$   
 (8) exists inverse under addition  
 $|v\rangle + |-v\rangle = |0\rangle$

### Linear independence

Set of  $N$  vectors  $|i\rangle$  such that any vector may be expanded

$$|v\rangle = \sum_{i=1}^N c_i |i\rangle$$

$N = \text{dimension of space}$

$|i\rangle$  form a basis.

$c_i = \text{complex numbers}$

Components  $c_i$  represent vector as column

$$|v\rangle \equiv \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix} \text{ in basis}$$

### Inner Product and Dual Space

Euclidean vectors

$$\vec{A} \cdot \vec{B} = \underbrace{(A_1, A_2, A_3)}_{\text{"}\vec{A}\text{"}} \begin{pmatrix} B_1 \\ B_2 \\ B_3 \end{pmatrix}$$

"A." linear map of vectors to scalars.

Generalize linear map

$$|v\rangle \xrightarrow{\langle w|} \text{scalar}$$

These maps form a linear vector space called the dual space with elements  $\langle w|$  "bra"  
Every vector has a dual

$$|v\rangle \doteq \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \quad \langle v| \doteq (v_1^*, v_2^*, \dots, v_n^*)$$

The Dirac bracket is the inner product

$$\langle v|w\rangle = (v_1^*, v_2^*, \dots, v_n^*) \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix}$$

Product is

- ①  $\langle v|w\rangle = \langle w|v\rangle^*$  skew symmetric
- ②  $\langle v|v\rangle \geq 0$  equality iff  $|v\rangle = |0\rangle$
- ③  $\langle v| (a|w\rangle + b|z\rangle) = a\langle v|w\rangle + b\langle v|z\rangle$

$$\langle a|w+bz\rangle = \langle v| (a|w+bz\rangle)^*$$

$$= a^* \langle w|v\rangle + b^* \langle v|z\rangle \quad \text{anti-linear}$$

convenient to choose orthonormal basis  $\{|i\rangle\}$

$$\langle i | j \rangle = \delta_{ij}$$

Gram-Schmidt construction  
complete basis  $\{|b_i\rangle\}$

$$|1\rangle = \frac{|b_1\rangle}{\sqrt{\langle b_1 | b_1 \rangle}}$$

$$|2'\rangle = |b_2\rangle - |1\rangle \langle 1 | b_2 \rangle$$

normalize  $|2\rangle = \frac{|2'\rangle}{\sqrt{\langle 2' | 2' \rangle}}$  , etc.

Schwartz Inequality

$$|\langle v | w \rangle| \leq \sqrt{\langle v | v \rangle} \sqrt{\langle w | w \rangle}$$

↑ complex norm  $|c| \equiv \sqrt{c^* c}$

triangle norm  $||v\rangle| \equiv \sqrt{\langle v | v \rangle}$

$$||v\rangle + |w\rangle| \leq ||v\rangle| + ||w\rangle|$$

Subspace subset of vector space  
forming its own vector space.

# Linear Operators

linear map  $|v\rangle \xrightarrow{\hat{T}} |v'\rangle$   
 I often use "hat" to denote operators.

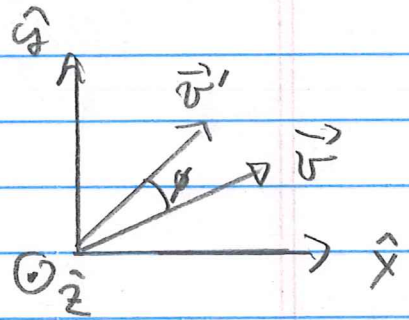
$$\hat{T} (a|a\rangle + b|b\rangle) = a(\hat{T}|a\rangle) + b(\hat{T}|b\rangle)$$

Example: Rotation of Euclidean vector

$$\hat{R} \begin{pmatrix} \hat{x} \\ \hat{y} \\ \hat{z} \end{pmatrix} \doteq \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$c \equiv \cos \phi$$

$$s \equiv \sin \phi$$



active as opposed to  
 passive change of basis

$$\hat{R}_x^E(\hat{O}_y) \hat{R}_z(\hat{O}_z) \neq \hat{R}_z^E \hat{R}_y \quad \text{rotations do not commute}$$

define commutator:

$$[S, \hat{T}] \equiv \hat{S}\hat{T} - \hat{T}\hat{S}$$

Projection operators, In basis  $\{|i\rangle\}$

$$|v\rangle = \sum v_i |i\rangle \doteq \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$$

$$\langle i|v\rangle = \sum_j v_j \underbrace{\langle i|j\rangle}_{\delta_{ij}} = v_i$$

$$\text{So } |v\rangle = \sum |i\rangle \langle i|v\rangle$$

$$\hat{I} = \sum |i\rangle \langle i| \quad \text{unit operator}$$

$$\hat{P}_i = |i\rangle \langle i| \quad \text{projection operator}$$

In basis, operators represented as matrices

$$|v'\rangle = \hat{T}|v\rangle = \sum_j \hat{T}|j\rangle \langle j|v\rangle$$

$$\langle i|v'\rangle = \langle i|\hat{T}|v\rangle$$

$$= \sum_j \underbrace{\langle i|\hat{T}|j\rangle}_{[T]_{ij}} \langle j|v\rangle$$

$$[T]_{ij}$$

$$v'_i = \sum_j [T]_{ij} v_j$$

sum on column index

$$\begin{pmatrix} v'_1 \\ v'_2 \\ \vdots \\ v'_n \end{pmatrix} = \begin{bmatrix} T_{11} & & \\ & \ddots & \\ & & T_{nn} \end{bmatrix} \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$$

Corresponding bra transforms as

$$|v'\rangle = \hat{T} |v\rangle$$

Defined

$$\langle v'| = \langle v| \hat{T}^\dagger$$

Hermitian

conjugate

$$\hat{T}^\dagger \triangleq (\hat{T}_{ij}^*)^T \quad \text{transpose}$$

$$\text{or } T_{ij}^\dagger = T_{ji}^*$$

Example: Pauli matrix

$$\hat{\sigma}_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \hat{\sigma}_y^\dagger$$

$$\hat{T}^\dagger = \hat{T} \quad \text{Hermitian matrix}$$

just as any complex number

$$c = \frac{c+c^*}{2} + \frac{c-c^*}{2}$$

real                  imaginary

any

$$\hat{T} = \frac{\hat{T} + \hat{T}^\dagger}{2} + \frac{\hat{T} - \hat{T}^\dagger}{2}$$

Hermitian

anti-Hermitian

$$A^\dagger = A$$

$$A^\dagger = -A$$

Important: easy to show that

Eigenvalues of Hermitian matrix are real  
Observables correspond to Hermitian operators

Unitary operator  $\hat{U}^\dagger \hat{U} = \hat{I}$

Scalar product invariant under  
 unitary transformation

$$\hat{U} |v\rangle = |v'\rangle$$

$$\hat{U}^\dagger |w\rangle = |w'\rangle$$

$$\langle w' | v' \rangle = \langle w | \hat{U}^\dagger \hat{U} | v \rangle = \langle w | v \rangle$$

Functions of operators.

Defined by Taylor expansion

$$f(\hat{A}) \equiv \sum_{i=0}^{\infty} \frac{1}{i!} \left. \frac{d^i f}{dx^i} \right|_{x=0} \hat{A}^i$$

Any unitary operator can be written as

$$\hat{U} = e^{i\hat{H}} \quad \hat{H} \text{ Hermitian}$$



Example: rotation operators are unitary

$$R^\dagger(\theta \hat{n}) = R^{-1}(\theta \hat{n}) = R(-\theta \hat{n})$$

$$R(\theta \hat{n}) = e^{-i\theta \hat{n} \cdot \vec{T}}$$

$\hat{T}_i$   $i=1,2,3$  are Hermitian generators

Example of Lie group pronounced "lee"  
continuous transformations. Almost all  
(and in particular relevant to us) properties  
follow from

$$[\hat{T}_i, \hat{T}_j] = i \sum_k f_{ijk} \hat{T}_k$$

structure constants

For quantum rotation group  $SU(2)$

$$\left[ \frac{\sigma_i}{2}, \frac{\sigma_j}{2} \right] = i \sum_k \epsilon_{ijk} \frac{\sigma_k}{2}$$

det = 1, unitary,  $2^2 - 1 = 3$   
generators

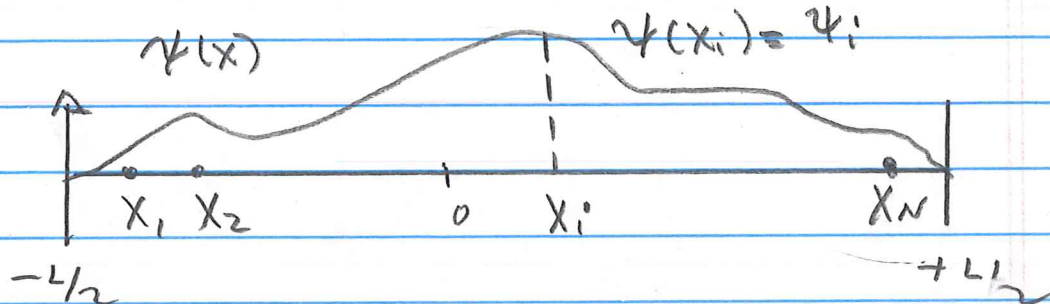
Einstein summation:  
repeated indices assumed to be summed.  
no need to write Sum symbol

lowest rep. is  $2 \times 2$  matrices

$\sigma_i$  Pauli matrices  $\frac{\sigma_i}{2}$  generators

structure constants just completely  
antisymmetric  $\epsilon_{ijk}$  symbol

Hilbert Space An  $\infty$  dimension, non denumerable vector space with complex functions as vectors.



N equally spaced points,  $N+1$  equal spaces of size

$$\Delta \equiv x_{n+1} - x_n = \frac{L}{N+1}$$

$$x_n = -\frac{L}{2} + n\left(\frac{L}{N+1}\right)$$

$$x_0 = -\frac{L}{2}, x_1 = -\frac{L}{2} + \Delta, \dots, x_N = \frac{L}{2} - \Delta, x_{N+1} = \frac{L}{2}$$

$\psi_i$  approximate  $\psi(x)$

$$|\psi\rangle \equiv \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix} \quad \text{form } N \text{ dimensional vector space}$$

$$|\psi\rangle + |\phi\rangle \equiv \begin{pmatrix} \psi_1 + \phi_1 \\ \psi_2 + \phi_2 \\ \vdots \\ \psi_N + \phi_N \end{pmatrix}$$

$$\langle \phi | \psi \rangle = \sum_{i=1}^N \phi_i^* \psi_i$$

basis vectors

$$|x_i\rangle \equiv \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \begin{array}{l} i^{\text{th}} \text{ element } 1 \\ \text{all others } 0 \end{array}$$

$$\langle x_i | x_j \rangle = \delta_{ij}$$

$$\psi(x_i) = \psi_i = \langle x_i | \psi \rangle$$

$$|\psi\rangle = \sum |x_i\rangle \psi(x_i) = \sum |x_i\rangle \langle x_i | \psi \rangle$$

In limit  $N \rightarrow \infty$  our inner product diverges. We should multiply by normalization factor  $\Delta = \frac{L}{N+1}$

$$\langle \phi | \psi \rangle = \lim_{N \rightarrow \infty} \sum_{i=1}^N \Delta \phi^*(x_i) \psi(x_i)$$

$$= \int_{-L/2}^{L/2} dx \phi^*(x) \psi(x)$$

Can also take  $L \rightarrow \infty$  if needed

$$\hat{I} = \int dx |x\rangle \langle x|$$

$$\langle x_i | x_j \rangle = \delta_{ij} \xrightarrow{\text{limit}} \langle x' | x \rangle = \delta(x' - x)$$

Dirac  $\delta$ -function not really a function, but represented by any function with property

$$\int_{-a}^{+a} f(x) \delta(x) dx = f(0)$$

"Spike" at  $x=0$  of unit area

most useful representation:

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} dk = \lim_{\lambda \rightarrow \infty} \frac{1}{\pi} \frac{\sin \lambda x}{x}$$

easy to see  $\delta(0) = \lim_{\lambda \rightarrow \infty} \frac{\lambda}{\pi}$

numerically, can show  $\int_{-a}^a \delta(x) dx = \lim_{\lambda \rightarrow \infty} \frac{1}{\pi} \int_{-a}^a \frac{\sin \lambda x}{x} dx = 1$

properties ①  $\delta(x) = \delta(-x)$  even

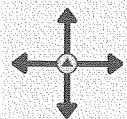
② Derivative of step  $\frac{d\theta(x-a)}{dx} = \delta(x-a)$

$$\text{step } \theta(x-a) \equiv \begin{cases} 0 & x < a \\ 1 & x > a \end{cases}$$

③  $\delta(f(x)) = \frac{\delta(x-x_0)}{\left| \frac{df}{dx} \right|_{x=x_0}}$  where  $f(x_0) = 0$

④ derivative

$$\delta'(x-x') = \frac{d}{dx}(x-x') = -\frac{d}{dx'}(x-x')$$



$$\int f(x') \delta'(x-x') dx' = \frac{d}{dx} \int f(x') \delta(x-x') dx'$$

$$= \frac{df}{dx}$$

$$\int f(x') \left( -\frac{d}{dx'} \delta(x-x') \right) dx' = \int \frac{df(x')}{dx'} \delta(x-x') dx' = \frac{df}{dx}$$

↑ integrate by parts

$$\therefore \frac{d}{dx} \delta(x-x') = \delta(x-x') \frac{d}{dx'}$$

Derivative operator.

$$D |f\rangle = \left| \frac{df}{dx} \right\rangle \quad \text{is not Hermitian}$$

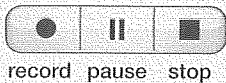
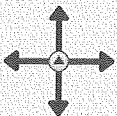
we can show  $K = \frac{1}{i} D$  is Hermitian

$$\langle g | K | f \rangle = \langle g | K f \rangle = \langle K f | g \rangle^* = \langle f | K^+ | g \rangle^*$$

$$\iint dx dx' \langle g | x \rangle \langle x | K | x' \rangle \langle x' | f \rangle$$

$$= \iint dx dx' g^*(x) \delta(x-x') \left( \frac{1}{i} \frac{d}{dx'} \right) f(x')$$

$$= \int dx g^*(x) \frac{1}{i} \frac{df}{dx}$$



record pause stop



jump



bookmark



0% jump to position 100%



playback speed



volume

$$\langle f | k^+ | g \rangle^*$$

$$= \left( \int dx f^* \left( \frac{1}{i} \frac{d}{dx} \right) g \right)^*$$

$$\frac{d}{dx}(fg^*) = \frac{df}{dx}g^* + f \frac{dg^*}{dx}$$

$$= - \int f \frac{1}{i} \frac{d}{dx} g^*$$

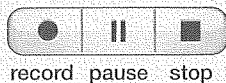
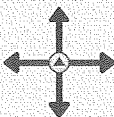
integrate by parts

$$fg^* \Big| + \int g^* \frac{1}{i} \frac{df}{dx} dx$$

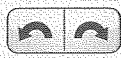
Hermitian if  
end point term vanishes

So in QM, wave functions required to  
vanish at  $\pm \infty$ , so Hermitian momentum  
operator is

$$\hat{P}_x = \frac{\hbar}{i} \frac{d}{dx}$$



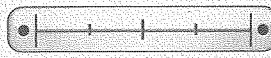
record pause stop



jump



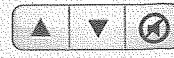
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0% jump to position 100%



playback speed



volume