

Lecture #1: Some Math Preliminaries

Quantum position states are vectors in an abstract space of complex functions with inner product - Hilbert space.

Recall Euclidean vectors:

$\vec{r} \doteq (x_1, x_2, x_3)$ in Cartesian coordinates
↑ "represented by"

Norm invariant under rotations. Introduce orthonormal basis vectors,

$$\hat{e}_i \cdot \hat{e}_j = \delta_{ij}$$

then
$$\vec{r} = \sum_{i=1}^3 x_i \hat{e}_i$$

Introduce Dirac abstract vector notation:

"ket" vector $|v\rangle$ element of linear vector space $\{|v\rangle\}$

- 1) addition $|c\rangle = |a\rangle + |b\rangle$ defined
- 2) complex scalar multiplication is distributive over vectors
 $a(|v\rangle + |w\rangle) = a|v\rangle + a|w\rangle$
- 3) scalar multiplication is distributive over scalars
 $(a+b)|v\rangle = a|v\rangle + b|v\rangle$
- 4) scalar multiplication is associative
 $a(b|v\rangle) = ab|v\rangle$

5) vector addition is commutative

$$|v\rangle + |w\rangle = |w\rangle + |v\rangle$$

6) vector addition associative

$$|v\rangle + (|w\rangle + |z\rangle) = (|v\rangle + |w\rangle) + |z\rangle$$

7) existence of null vector $|0\rangle$.

$$|0\rangle + |v\rangle = |v\rangle$$

8) existence of additive inverse $|-v\rangle$.

$$|v\rangle + |-v\rangle = |0\rangle$$

Linear Independence Exist set of N vectors $|i\rangle$ such that any vector may be expanded

$$|v\rangle = \sum_{i=1}^N c_i |i\rangle$$

c_i complex scalars
 $N = \text{dimension of space}$

then $\{|i\rangle\}$ are said to form a basis.

Components c_i represent vector as a column

$$|v\rangle \doteq \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix} \quad \uparrow \text{basis}$$

Inner Product and Dual Space

recall Euclidean vector inner product in Cartesian coordinates,

$$\vec{A} \cdot \vec{B} = \underbrace{(A_1, A_2, A_3)}_{\text{"}\vec{A}\text{"}} \begin{pmatrix} B_1 \\ B_2 \\ B_3 \end{pmatrix}$$

" \vec{A} " is a linear map of vectors to scalars

Generalize as

$$|w\rangle \xrightarrow{\langle w|} \text{scalar}$$

These maps form a linear vector space called the dual space with element $\langle w|$ "bra".

Every vector has a dual

$$|v\rangle \doteq \begin{pmatrix} v_1 \\ \vdots \\ v_N \end{pmatrix} \quad \langle v| \doteq (v_1^*, \dots, v_N^*)$$

The Ditac bracket is the inner product

$$\langle v|w\rangle = (v_1^*, v_2^*, \dots, v_N^*) \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{pmatrix} = \text{scalar}$$

Inner product is:

1) skew symmetric $\langle v|w \rangle = \langle w|v \rangle^*$

2) $\langle v|v \rangle = 0$ iff $|v\rangle = |0\rangle$

3) antilinear

$$\langle v | (a|w\rangle + b|z\rangle) = a\langle v|w\rangle + b\langle v|z\rangle$$

$$= |aw + bz\rangle$$

$$\langle aw + bz | v \rangle = \langle v | aw + bz \rangle^*$$

$$= a^* \langle w | v \rangle + b^* \langle z | v \rangle$$

Orthonormal Basis $\{|i\rangle\}$

$$\langle i | j \rangle = \delta_{ij}$$

may be constructed by Gram-Schmidt procedure
Given any basis $\{|b_i\rangle\}$

$$|1\rangle = \frac{|b_1\rangle}{\sqrt{\langle b_1 | b_1 \rangle}}$$

$$|2'\rangle = |b_2\rangle - |1\rangle(\langle 1 | b_2 \rangle)$$

subtract
component
|| to $|1\rangle$

normalize $|2\rangle = \frac{|2'\rangle}{\sqrt{\langle 2 | 2 \rangle}}$

etc.

Schwarz Inequality:

$$|\langle v|w \rangle| \leq \sqrt{\langle v|v \rangle} \sqrt{\langle w|w \rangle}$$

\hat{C} denotes complex norm $|C| \equiv \sqrt{C^* C}$

and $||v\rangle| \equiv \sqrt{\langle v|v \rangle}$

Triangle Inequality

$$||v\rangle + |w\rangle| \leq ||v\rangle| + ||w\rangle|$$

Subspace subset of vector space forming its own vector space.

Linear Operators

$$\text{linear map } |v\rangle \xrightarrow{\hat{T}} |v'\rangle$$

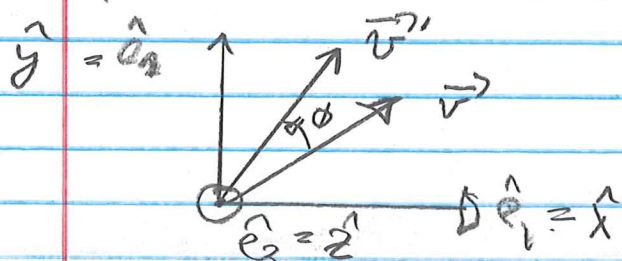
often use "hat" to denote operators for clarity.

$$\begin{aligned} \text{linearity: } \hat{T}(a|v\rangle + b|w\rangle) \\ = a(\hat{T}|v\rangle) + b(\hat{T}|w\rangle) \end{aligned}$$

Example of linear operator - rotation of Euclidean vector.

active rotation - rotates vector

passive rotation - rotates basis



note: "hat" also denotes unit vector

active right-handed rotation by angle ϕ

operator represented by matrix

$$\hat{R}^E(\phi \hat{z}) = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{array}{l} c \equiv \cos \phi \\ s \equiv \sin \phi \end{array}$$

$$v_1' = c v_1 - s v_2, \text{ etc.}$$

Rotations do not commute

$$\hat{R}^E(\phi \hat{y}) \hat{R}^E(\phi \hat{z}) \neq \hat{R}^E(\phi \hat{z}) \hat{R}^E(\phi \hat{y})$$

Define commutator bracket:

$$[\hat{S}, \hat{T}] \equiv \hat{S} \hat{T} - \hat{T} \hat{S} = -[\hat{T}, \hat{S}]$$

identities:
(drop hats)

$$[a, b+c] = [a, b] + [a, c]$$

$$[a, bc] = b[a, c] + [a, b]c$$

$$[ab, c] = a[b, c] + [a, c]b$$

Projection Operator. In basis $\{|i\rangle\}$

$$|v\rangle = \sum_j v_j |j\rangle \equiv \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$$

$$\langle i | v \rangle = \sum_j v_j \underbrace{\langle i | j \rangle}_{\delta_{ij}} = v_i$$

so completeness is

i is 'dummy' index

$$|v\rangle = \sum_i |i\rangle \langle i | v \rangle$$

Then unit operator can be written as

$$\hat{I} = \sum_i |i\rangle \langle i|$$

projection operator

note convenient notation " $|i\rangle \langle i|$ "

maps vector to vector
so operator in basis.

$$\hat{P}_i = |i\rangle \langle i|$$

In basis, operators are represented as matrices

$$|v'\rangle = \hat{T} |v\rangle = \sum_j \hat{T} |j\rangle \underbrace{\langle j | v \rangle}_{v_j \text{ component}}$$

$$\langle i | v' \rangle = \sum_j \underbrace{\langle i | \hat{T} | j \rangle}_{\text{matrix } [T]_{ij}} \langle j | v \rangle$$

matrix $[T]_{ij}$

com

$$v'_i = \sum_j [T]_{ij} v_j$$

sums column index

or

$$\begin{pmatrix} v_1' \\ v_2' \\ \vdots \\ v_N' \end{pmatrix} = [T]_{ij} \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_N \end{pmatrix}$$

Hermitian Conjugate defined by

$$|v'\rangle = \hat{T}^\dagger |v\rangle$$

$$\langle v'| = \langle v| \hat{T}^\dagger$$

$$\hat{T}^\dagger = (\hat{T}_{ij})^\dagger = (\hat{T}_{ji})^*$$

T denotes transpose

matrix $\hat{T}_{ij}^\dagger = \hat{T}_{ji}^*$

Example Pauli y-matrix

$$\sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \sigma_y^\dagger$$

$$\hat{T}^\dagger = \hat{T} \text{ is said to be Hermitian}$$

Just as any complex number

$$c = \frac{c+c^*}{2} + \frac{c-c^*}{2}$$

real + imaginary

any operator

$$T = \frac{T+T^\dagger}{2} + \frac{T-T^\dagger}{2}$$

Hermitian

$$A^\dagger = A$$

anti-Hermitian

$$A^\dagger = -A$$

Eigenvalue Problem Eigenvectors of operator \mathcal{R}

$$\mathcal{R} |w\rangle = w |w\rangle \quad |w\rangle \text{ eigenvector}$$

w eigenvalue (complex scalar)

convenient to label eigenvector, with eigenvalue

then eigenvalue problem is to find w & $|w\rangle$.

$$(\mathcal{R} - w\mathcal{I}) |w\rangle = 0 \quad \mathcal{I} \equiv \text{identity operator}$$

operator $(\mathcal{R} - w\mathcal{I})$ cannot have inverse for $|w\rangle$ to exist. Introduce basis $\{|i\rangle\}$

$$\sum_i \langle i | (\mathcal{R} - w\mathcal{I}) | j \rangle \langle j | w \rangle = 0$$

$$\sum_j (\mathcal{R}_{ij} - w \delta_{ij}) w_j = 0 \quad \text{using matrix notation}$$

then

$\det(\mathcal{R}_{ij} - w \delta_{ij}) = 0$ gives characteristic equation, a polynomial in w for N eigenvalues.

Similarity transformation: matrix S with eigenvectors as columns diagonalizes \mathcal{R} as

$$S^\dagger \mathcal{R} S = \text{diag}(w_1, w_2, \dots, w_N)$$

Shankar: Hermitian and Unitary operators have N eigenvalues. Only for Hermitian operators are eigenvalues guaranteed to be real, with orthogonal eigenvectors.

Easy to prove that eigenvalues of any Hermitian operator are real scalars. $|w\rangle$ normalized eigenvector

$$\hat{A}|w\rangle = w|w\rangle \quad (1)$$

$$\langle w|\hat{A}^\dagger = \langle w|\hat{A} = \langle w|w^* \quad (2)$$

operate on (1) with bra $\langle w|$ and on (2) with ket $|w\rangle$,

$$\begin{cases} \langle w|\hat{A}|w\rangle = w \\ \langle w|\hat{A}|w\rangle = w^* \end{cases} \Rightarrow \begin{cases} w - w^* = 0 \\ w = w^* \end{cases}$$

Eigenvectors of Hermitian operators are orthogonal

Consider two eigenvalues w_a, w_b of \hat{A} ,

$$\langle w_b|\hat{A}|w_a\rangle = w_a \langle w_b|w_a\rangle \quad (3)$$

$$\langle w_a|\hat{A}|w_b\rangle = w_b \langle w_a|w_b\rangle \quad (4)$$

take c.c. of both sides of (4):

$$\begin{aligned} \langle w_a|\hat{A}|w_b\rangle^* &= \langle w_b|\hat{A}^\dagger|w_a\rangle = \langle w_b|\hat{A}|w_a\rangle \\ &= w_a^* \langle w_b|w_a\rangle \end{aligned} \quad (5)$$

c.c. of left hand side

then (3)-(5) gives $0 = (w_a - w_b) \langle w_b|w_a\rangle$

then $\langle w_b|w_a\rangle = 0$ if $w_a \neq w_b$. For normalized eigenvectors

$$\langle w_b|w_a\rangle = \delta_{ba}$$

Unitary operator $U^\dagger U = I$

The Dirac product is invariant under a unitary transformation.

$$U|v\rangle = |v'\rangle$$

$$U|w\rangle = |w'\rangle$$

$$\langle w'|v'\rangle = \langle w|U^\dagger U|v\rangle = \langle w|v\rangle$$

Functions of Operators are defined by Taylor expansion,

$$f(\hat{A}) \equiv \sum_{n=0}^{\infty} \frac{1}{n!} \left. \frac{d^n f(x)}{dx^n} \right|_{x=0} \hat{A}^n$$

Any unitary operator may be written as

$$U = e^{iH} \quad \text{where } H \text{ is Hermitian}$$

Example: Euclidean rotations.

are unitary: $R^\dagger(\theta \hat{n}) = R^{-1}(\theta \hat{n}) = R(-\theta \hat{n})$

$$\text{so } R^\dagger R = I$$

introduce vector $\vec{\theta} = \sum \theta_i \hat{e}_i$ Euclidean vector

Then $R(\vec{\theta}) = e^{-i\vec{\theta} \cdot \vec{T}}$ minus gives right handed rotation

where T_i are 3 Hermitian operators called generators.

What is a group?

A set of elements $\{g_i\}$ with a
combination rule (called group multiplication)

① $g_a \circ g_b = g_c$ every pair a, b
with c in group

② associative $g_a \circ (g_b \circ g_c) = (g_a \circ g_b) \circ g_c$

③ existence of identity element I

$$I \circ g_a = g_a \circ I = g_a$$

④ existence of inverse for every element

$$g_a \circ g_a^{-1} = g_a^{-1} \circ g_a = I$$

In general, N generators with commutators

$$[T_i, T_j] = i \sum_k \underbrace{f_{ijk}}_{\text{real "structure constants"}} T_k$$

↑
Hermitian

The rotations in Q.M., groups is $SU(2)$.

generators of $SU(N) = N^2 - 1$, So 3.

A representation is an explicit set of matrices that also have generators T_i or matrices.

So $RE(\vec{\theta})$ are explicit group elements that act on a 3-dim vector space.

$$T_i = i \frac{dR}{d\theta_i} \Big|_{\vec{\theta}=0} = i \frac{d}{d\theta_i} (1 - i \vec{\theta} \cdot \vec{T} + \dots) \Big|_{\vec{\theta}=0}$$

Rotation Group is $SU(2)$: $\det=1$, lowest dimensional (defining) representation 2×2 . Group elements have $\det=1$.
 2×2 Hermitian generators are Pauli matrices $\frac{\sigma_i}{2}$.

Pauli: $\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $\sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$ $\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

traces, Hermitian. $SU(2)$ structure

constants are ϵ_{ijk} completely anti-symmetric

symbol: $\epsilon_{123} = \epsilon_{132}$ etc. $\epsilon_{112} = 0$, etc.

$$\left[\frac{\sigma_i}{2}, \frac{\sigma_j}{2} \right] = i \sum_k \epsilon_{ijk} \frac{\sigma_k}{2}$$

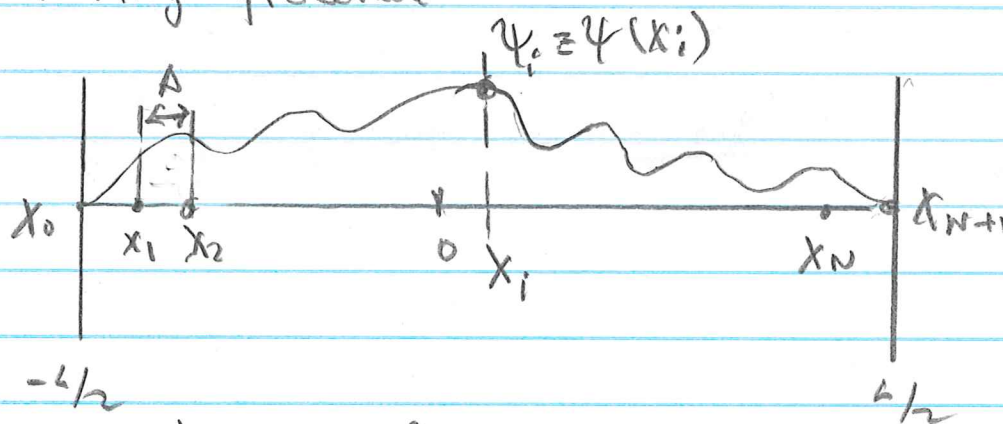
2x2 Representation acts on a 2-dim, complex

spinor:

$$\chi = \begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix}$$

Hilbert Space A non-denumerably infinite Vector space with complex functions as vectors,

Limiting procedure -



N equally spaced points, N+1
space of size

$$\Delta = x_{i+1} - x_i = \frac{L}{N+1}$$

$$x_0 = -\frac{L}{2}, x_1 = -\frac{L}{2} + \Delta, \dots, x_N = \frac{L}{2} - \Delta, x_{N+1} = \frac{L}{2}$$

ψ_i approximates $\psi(x)$

$$|\psi\rangle \doteq \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \\ \psi_N \end{pmatrix}$$

N dimensional
Vector space

$$|\psi\rangle + |\phi\rangle \doteq$$

$$\begin{pmatrix} \psi_1 + \phi_1 \\ \psi_2 + \phi_2 \\ \vdots \\ \psi_N + \phi_N \end{pmatrix}$$

inner product:

$$\langle \phi | \psi \rangle = \sum_{i=1}^N \phi_i^* \psi_i$$

basis vectors are:

$$|x_i\rangle = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow \begin{array}{l} i\text{th element is } 1 \\ \text{all others are } 0. \end{array}$$

obviously

$$\langle x_i | x_j \rangle = \delta_{ij}$$

so

$$\langle x_i | \psi \rangle = \psi_i = \psi(x_i) \quad \text{and}$$

$$|\psi\rangle = \sum |x_i\rangle \langle x_i | \psi \rangle = \sum \psi(x_i) |x_i\rangle$$

Hilbert space is limit $N \rightarrow \infty$. Inner product diverges, we should multiply by normalization factor $\Delta = \frac{L}{N+1}$

$$\langle \phi | \psi \rangle = \lim_{N \rightarrow \infty} \sum \Delta \phi^*(x_i) \psi(x_i)$$

$$= \int_{-L/2}^{L/2} dx \phi^*(x) \psi(x)$$

can easily extend to $L \rightarrow \infty$.

Completeness of basis,

$$I = \int dx |x\rangle \langle x|$$

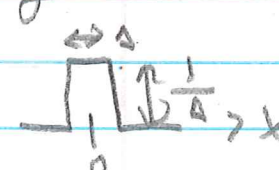
$$\langle x_i | x_j \rangle = \delta_{ij} \xrightarrow{N \rightarrow \infty} \langle x' | x \rangle \equiv \delta(x' - x)$$

Kronecker δ Dirac δ function

δ -function is not a function but a distribution, that is any function with limiting property

$$\int_{-a}^a f(x) \delta(x) dx = f(0)$$

a , any interval containing $x=0$.

Conceptually, unit area spike at $x=0$, 

most useful representation

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} dk = \lim_{\lambda \rightarrow \infty} \frac{1}{\pi} \frac{\sin \lambda x}{x}$$

easy to show, $\delta(0) = \lim_{\lambda \rightarrow \infty} \frac{\lambda}{\pi} \rightarrow \infty$ diverge

and less easy but

$$\int_{-a}^a \delta(x) dx = \lim_{\lambda \rightarrow \infty} \frac{1}{\pi} \int_{-a}^a \frac{\sin \lambda x}{x} dx = 1$$

Properties:

1) even $\delta(x) = \delta(-x)$

2) derivative of step $\theta(x-a) = \begin{cases} 0 & x < a \\ 1 & x > a \end{cases}$

$$\frac{d\theta}{dx} = \delta(x-a)$$

3) $\delta(f(x)) = \frac{\delta(x-x_0)}{\left| \frac{df}{dx} \right|_{x=x_0}}$ where $f(x_0) = 0$

4) derivative

$$\frac{d}{dx} \delta(x-x') = \delta'(x-x') = -\frac{d}{dx'} \delta(x-x')$$

and thus

$$\int f(x) \delta'(x-x') dx = \frac{d}{dx} \int f(x) \delta(x-x') dx$$

$$= f(x) = \int f(x') \left[-\frac{d}{dx'} \delta(x-x') \right] dx'$$

$$= \int \delta(x-x') \frac{d}{dx'} f(x') dx'$$

integrate by parts, $f(x') \rightarrow 0$ as $x' \rightarrow \infty$

$$\delta'(x-x') = \delta(x-x') \frac{d}{dx'}$$

Derivative operator $\frac{d}{dx}$ is not Hermitian, but
 momentum operator $\frac{P_x}{\hbar} = \frac{1}{i} \frac{d}{dx} \equiv K_x$ is Hermitian
 need to show wave number op.

$$\langle \phi | K_x \psi \rangle = (\langle K_x \psi | \phi \rangle)^* = (\langle \psi | K_x^\dagger \phi \rangle)^*$$

must equal $(\langle \psi | K_x \phi \rangle)^*$

work backwards,

$$\begin{aligned} (\langle \psi | K_x \phi \rangle)^* &= \left(\int \psi^* \frac{1}{i} \frac{d}{dx} \phi dx \right)^* \\ \text{integrate by part} &= \left[\phi^* \frac{d\psi}{dx} \right]_{-\infty}^{\infty} - \left(\int \phi \frac{\hbar}{i} \psi^* dx \right)^* \\ &\quad \uparrow \\ &\text{must go to 0 at } \pm \infty \quad = + \int \phi^* \frac{\hbar}{i} \psi dx \\ &= \langle \phi | K_x \psi \rangle \quad \checkmark \end{aligned}$$

so operator $\frac{\hbar}{i} \frac{d}{dx} = P_x$ is Hermitian, $P_x^\dagger = P_x$
 with real eigenvalues.