- 1. Given a matrix A with eigenvalues  $a_i$ prove that  $\operatorname{Tr}(A) = \sum a_i$
- 2. Consider a classical collection of masses  $m_i$  and positions  $\vec{r_i}$  rotating with about a fixed axis with angular velocity  $\vec{\omega}$ . The velocites are therefore  $\vec{v_i} = \vec{\omega} \times \vec{r_i}$ .

In general, will the angular momentum be parallel to  $\vec{\omega}$ ?

Argue that in general there will be three directions for  $\vec{\omega}$  that if chosen will have the angular momentum be parallel to this direction. How do you find these directions?

3. Prove that, given a function f(x) which has a zero  $f(x_0) = 0$ ,

$$\delta(f(x)) = \frac{\delta(x_0 - x)}{\left|\frac{df}{dx}|_{x_0}\right|}$$

Hint: On hw 1 you prove that  $\delta(ax) = \delta(x)/|a|$ .

4. Prove that

$$\delta(x - x') = \frac{d}{dx}\theta(x - x')$$

where  $\theta$  is the unit step function.